Python with Robots **Mission 7 Lab Data Sheet** **OBJ 2 – Power**	**Name:**

<u>Testing **Power**</u>

An emitter power level setting from 1 (low power) to 8 (high power) controls the brightness of CodeBot's IR "flashlight."

power = 1
thresh = 75

Color of surface	**Distance (cm) for** True
Open space	
Black	
Gray	
White	

power = 4
thresh = 75

Color of surface	**Distance (cm) for** True
Open space	
Black	
Gray	
White	

power = 8
thresh = 75

Color of surface	**Distance (cm) for** True
Open space	
Black	
Gray	
White	